



# **Series 4440 Ruggedized Digital Portable Air Velocity Meter User's Guide**

**August 1990**

# Unit Description Sheet

**Complete Model Number:** \_\_\_\_\_

**Serial Number:** \_\_\_\_\_

**Kurz Order Number:** \_\_\_\_\_

**Customer P. O. Number:** \_\_\_\_\_

**Calibration Temperature:**  Standard (25° C, 77° F)  
 Other (specify): \_\_\_\_\_

**Calibration Pressure:**  Standard (760 mm Hg, 29.92 in Hg)  
 Other (specify): \_\_\_\_\_

**Velocity Ranges:**  0-2,000 & 0-6,000 SFPM  
 0-2,000 & 0-12,000 SFPM  
 0-10 & 0-30 SMPS  
 0-10 & 0-60 SMPS  
 Other (specify): \_\_\_\_\_

**Probe-Support Construction:**  316 Stainless Steel

**Probe-Support Extenders:**  4 18"  
 Other      Number: \_\_\_\_\_ Length: \_\_\_\_\_

**Sensor:**  Standard Rated to 250° C  
 HHT Rated to 500° C  
 Custom Cable Length: \_\_\_\_\_

**Notes:** \_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_  
\_\_\_\_\_

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2411 Garden Road

Monterey, CA 93940

(408) 646-5911

(800) 424-7356

Document Title: *Model 4440 Portable Digital Air Velocity and Temperature Meter User's Guide*

Document Number: 360139 Rev. B

Publication Date: August 1990

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## **Warranty Statement**

The Kurz Model 4440 Portable Digital Air Velocity and Temperature Meter is warranted to be free from defects in material or workmanship for one year from the date of shipment from the factory. Kurz's obligation is limited to repairing, or at its option, replacing products and components that, on verification, prove to be defective. Warranty work will be performed at the factory in Monterey, California. Kurz shall not be liable for installation charges, for expenses of buyer for repairs or replacement, for damages from delay or loss of use, or other indirect or consequential damages of any kind. Kurz extends this warranty only upon proper use and/or installation of the product in the application for which it is intended and does not cover products that have been serviced or modified by any person or entity other than Kurz Instruments Incorporated and its authorized service technicians. This warranty does not cover damaged sensors, units that have been subjected to unusual physical or electrical stress, or upon which the original identifications marks have been removed or altered.

Transportation charges for material shipped to the factory for warranty repair are to be paid for by the shipper. Kurz will return items repaired or replaced under warranty prepaid. No items shall be returned for warranty repair without prior authorization from Kurz. Call Kurz Instruments service department at (408) 646-5911 to obtain a return authorization number.

This warranty contains the entire obligation of Kurz Instruments Incorporated. No other warranties, expressed, implied, or statutory are given.

## **Important Notice**

The MetalClad sensor used in the 4440 Portable Digital Air Velocity and Temperature Meter produces heat during normal operation. The sensor is designed for use in flows of air and other NONEXPLOSIVE gases. **DO NOT USE THIS SENSOR IN FLOWS OF EXPLOSIVE GASES. FAILURE TO HEED THIS WARNING COULD RESULT IN EXPLOSION, DAMAGE TO FACILITIES, SERIOUS INJURY, OR DEATH.**

# Table of Contents

<b>About This Book</b> .....	<b>ix</b>
<b>Quick Set-Up Guide</b> .....	<b>xi</b>
<b>Section 1: Product Overview</b> .....	<b>1-1</b>
1.1 Description .....	1-1
1.2 How the Sensor Works .....	1-2
1.3 Features and Specifications .....	1-5
<b>Section 2: Assembly and Orientation</b> .....	<b>2-1</b>
2.1 Assembly .....	2-1
2.1.1 Adding Probe-Support Extenders (Optional) .....	2-1
2.1.2 Adding the Sensor-Alignment Attachment (Optional) .....	2-2
2.1.3 Connecting the Sensor Cable .....	2-3
2.1.4 Connecting the DC Power Cable .....	2-4
2.2 Controls and Connectors .....	2-4
2.2.1 Range Selector Knob .....	2-5
2.2.2 Slow/Fast Toggle .....	2-6
2.2.3 Display/Hold Toggle .....	2-7
2.2.4 Output Connectors .....	2-7
<b>Section 3: Operation</b> .....	<b>3-1</b>
3.1 Selecting a Location .....	3-1
3.2 Taking a Velocity Reading .....	3-2
3.3 Taking a Temperature Reading .....	3-3

3.4 Velocity Averaging .....	3-3
3.4.1 Half-Traversal Averaging .....	3-3
3.4.2 Double-Traversal Averaging .....	3-6
3.5 Calculating Actual Velocities .....	3-8
<b>Section 4: Maintenance .....</b>	<b>4-1</b>
4.1 Taking Care of the External Battery Pack .....	4-1
4.2 Cleaning the Sensor .....	4-2
4.3 Recalibration .....	4-2
<b>Appendix A .....</b>	<b>A-1</b>
<b>Index .....</b>	<b>Index-1</b>
<b>Figures</b>	
1-1. <i>4440 Basic Components</i> .....	1-2
1-2. <i>MetalClad Sensor</i> .....	1-3
1-3. <i>Sensor Output vs Flow</i> .....	1-4
1-4. <i>Linearized Output</i> .....	1-5
2-1. <i>Sensor-Alignment Attachment</i> .....	2-2
2-2. <i>Sensor Cable and Meter Box Connectors</i> .....	2-3
2-3. <i>DC Power Cable Connections</i> .....	2-4
2-4. <i>4440 Controls and Connectors</i> .....	2-5
3-1. <i>Probe Location</i> .....	3-1
3-2. <i>Equal-Area Half Traverse</i> .....	3-5
3-3. <i>Equal-Area Double Traverse</i> .....	3-7
<b>Tables</b>	
1-1. <i>4440 Specifications</i> .....	1-7
2-1. <i>Linear Output Voltages</i> .....	2-8
3-1. <i>Half-Traversal Velocity Averaging Example</i> .....	3-6
3-2. <i>Double-Traversal Velocity Averaging Example</i> .....	3-8

## About This Book

This book contains four sections and an appendix, each of which is briefly described below. The book also contains a Unit Description Sheet and an index. The book is not designed to be read cover to cover; rather, it is designed to present information to the 4440 user in as accessible a manner as possible.

### Organization

#### Unit Description Sheet

This sheet is found in the front of the book, immediately following the title page. It contains important identifying information about your Model 4440 Portable Digital Air Velocity and Temperature Meter, including model number, serial number, Kurz order number, and customer purchase order number. It also lists any options you ordered with your 4440. Check the options listed against your original order and against the actual contents of the shipping carton. Report any discrepancies immediately to Kurz Instruments Incorporated at (408) 646-5911.

#### Quick Set-Up Guide

The Quick Set-Up Guide is a chart summarizing some of the information presented in the rest of the manual. It shows you how to hook up the 4440 for use and how to charge the external battery pack.

#### Section 1: Product Overview

This section introduces you to the purpose, principles of operation, and features of the Model 4440. You can safely skip this section if you are already familiar with that information.

#### Section 2: Assembly and Orientation

Section 2 explains how to assemble the 4440 and provides detailed explanations of each of the unit's controls and connectors.

#### Section 3: Operation

This section explains how to obtain accurate velocity and temperature readings with the 4440, how to average velocity readings, and how to calculate actual velocities from the standard velocities reported by the 4440.

#### Section 4: Maintenance

This section explains how to take care of the 4440's external battery pack, how to clean the sensor when necessary, and how to get your 4440 periodically recalibrated.

## **Appendix A: Component Layout and Schematic Drawings**

The appendix contains detailed component layout drawings and circuit diagrams of the 4440. This information is not needed by most 4440 users in routine operation of the unit. It is provided as an aid to those users who want to perform detailed maintenance and testing.

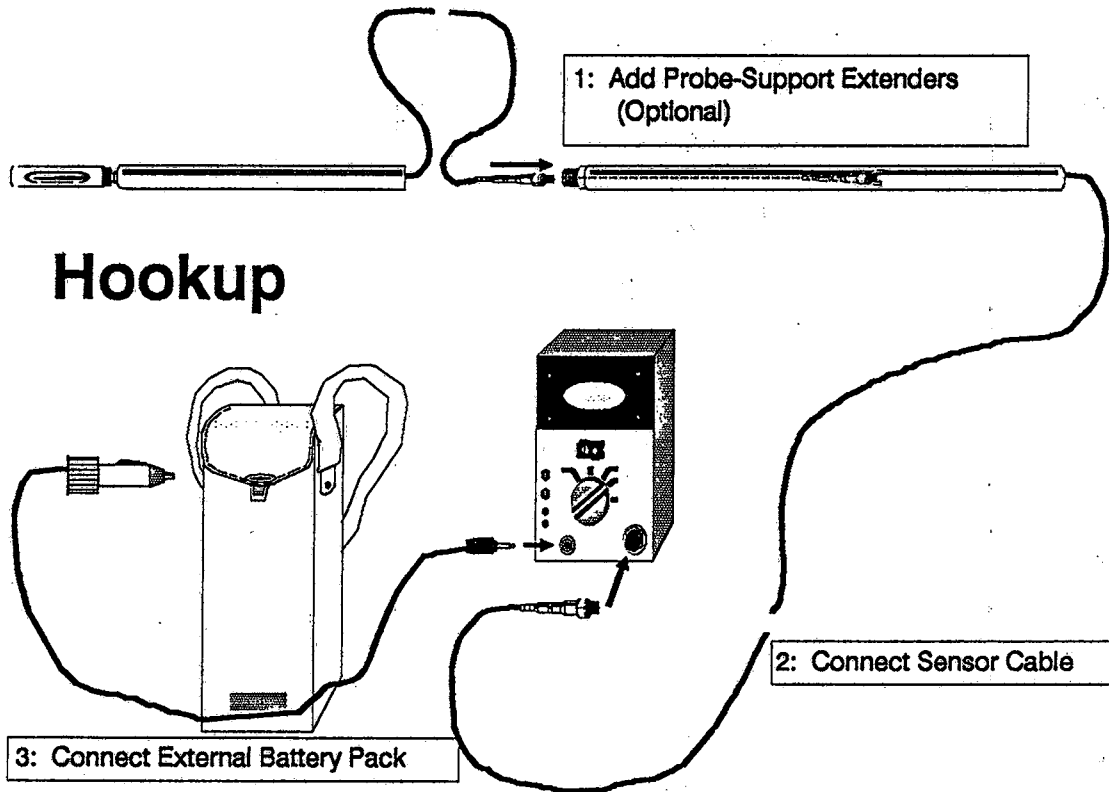
### **About the Art in This Book**

The computer-generated art in the main sections of this book is intended to illustrate particular points under discussion. It includes only as much detail as is relevant to the discussion at hand. No attempt has been made to accurately scale these drawings or to include details not under discussion in the text that precedes and follows each drawing. If you need more detailed and precise visual information, refer to Appendix A, which contains reproductions of actual engineering drawings.

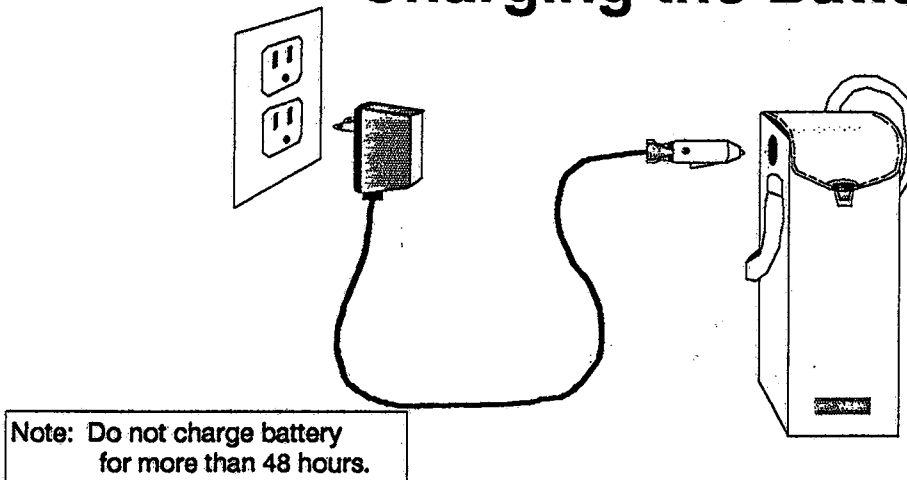


## Quick Set-Up Guide

The chart below shows you how to hook up the 4440 for use and how to charge the external battery pack. Please note that the rest of the manual contains important information not covered by this chart.



## Charging the Battery



## **Section 1: Product Overview**

This section contains a general description of the Model 4440 Portable Digital Air Velocity and Temperature Meter. It explains how the meter works and lists its features and specifications.

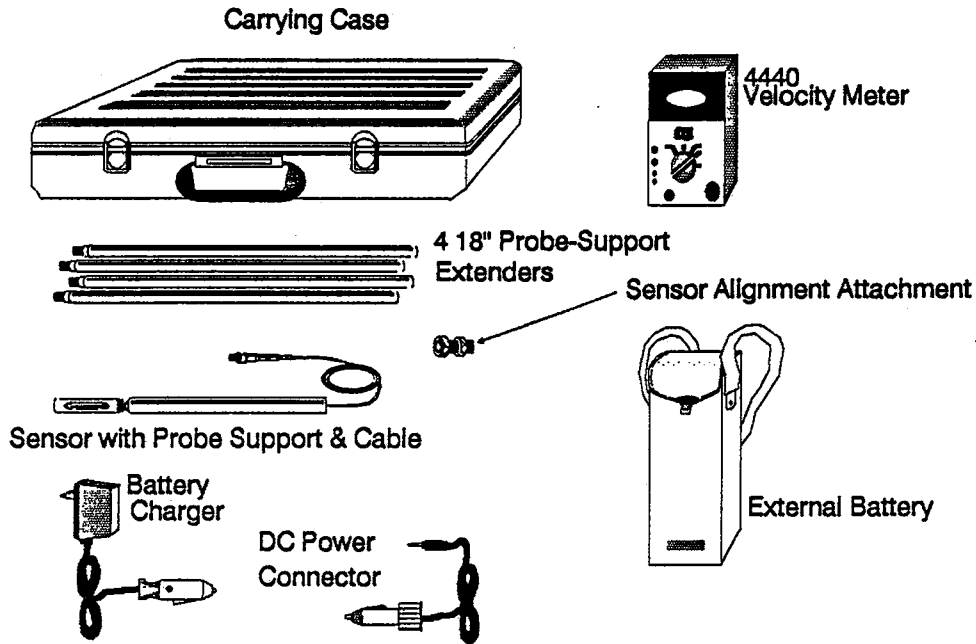
### **1.1 Description**

The Model 4440 Portable Air Velocity and Temperature Meter is designed to monitor the velocity and temperature of air within pipes, stacks, flues, and similar enclosed channels. It can also be used for monitoring air velocity in open areas, but its extreme ruggedness and resistance to contamination render the 4440 particularly suitable for hot, dirty, or corrosive industrial environments.

The basic components of the 4440 are listed below and shown in Figure 1-1.

- The 4440 meter itself, housed in a high-impact plastic case and containing all necessary controls and connectors
- MetalClad™ all-metal flow sensor mounted inside a protective window at one end of its attached probe support
- 15 feet of sensor cable preattached to the sensor
- Stainless steel probe support
- Four 18" stainless steel probe-support extenders
- External 12 Vdc, 6 amp/hr. battery pack with carrying case and shoulder strap
- 110 Vac battery charger
- 12 Vdc power cable
- Foam-padded carrying case

Figure 1-1. 4440 Basic Components

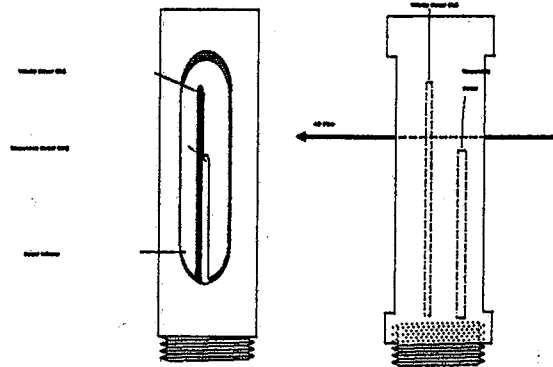


## 1.2 How the Sensor Works

The 4440's MetalClad sensor is in fact two sensor elements in one: a temperature sensor and a velocity sensor. Each sensor element consists of a reference-grade platinum winding wound around a ceramic mandrel and enclosed in a stainless steel sheath. The temperature sensor is the shorter of the two sensor elements housed within the MetalClad's protective window; the velocity sensor is the longer sensor element.

Figure 1-2 shows two views of the MetalClad sensor within its protective sensor window. Note the direction of the airflow shown in Figure 1-2. When you use the 4440, always make sure that the temperature sensor ( $R_{tc}$ ) is upstream of the velocity sensor ( $R_p$ ). This orientation results in more accurate readings.

Figure 1-2. *MetalClad Sensor: Two Views*



The temperature sensor senses the ambient temperature of the air flow. The velocity sensor is then heated to approximately 75° to 100° F above the ambient temperature and is maintained at the same level of temperature differential (overheat) above the ambient temperature regardless of changes in ambient temperature or air velocity.

**CAUTION:** The MetalClad sensor's standard rating is for nonexplosive gases. If you plan to use it in flows of explosive gases, Kurz strongly recommends that you purchase the optional probe safety circuit. That circuit prevents the velocity sensor from ever reaching the ignition temperature of a specified gas, provided the temperature of the gas flow itself is kept within appropriate guidelines. Contact Kurz Instruments for more information on using the MetalClad sensor in explosive gas flows.

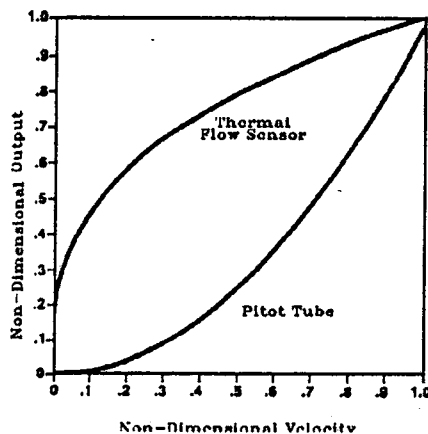
Because the temperature sensor compensates for fluctuations in ambient temperature, the amount of electrical power needed to maintain the velocity sensor's overheat is affected only by the velocity of air over the sensor: The greater the velocity of the flow, the greater its cooling effect on the sensor and the greater the electrical power needed to maintain the sensor's overheat. It is this power draw that is measured by the 4440.

Because the sensor is directly measuring mass velocity (i.e., the number of molecules carrying heat away from the velocity sensor), it is calibrated in standard units, which are referenced to a temperature of 25° C and atmospheric pressure of 760 mm Hg. In other words, air at 25° C and 760 mm Hg, flowing past the sensor at 100 feet per minute (FPM) will produce a reading of 100 standard feet per minute (SFPM). A 100 FPM flow at a different temperature or pressure produces a reading in SFPM that accurately compensates for the temperature or pressure differential.

The temperature and velocity sensors form two legs of a balanced Wheatstone bridge. The bridge circuitry itself is contained in the 4440 meter box. The printed circuit board housed in the meter box has two main functions: to supply current to the sensor and to transform the nonlinear current draw received from the sensor into a linear signal that can then be digitized for display.

The draw from the sensor is nonlinear in that the amount of power needed to maintain the velocity sensor's overheat is not directly proportionate to the velocity of the airflow. Instead, the power-consumption curve is fairly steep at low flow rates and relatively flatter at higher rates of flow. Figure 1-3 shows the MetalClad sensor's output curve as flow increases<sup>1</sup>. Figure 1-3 also shows the corresponding curve for a pitot-tube type sensor. Note the greatly superior sensitivity of the MetalClad sensor at low flow rates.

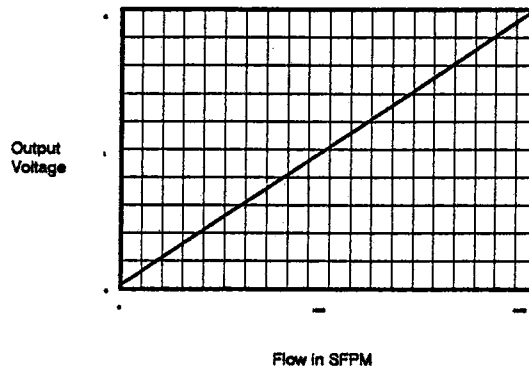
Figure 1-3. *Sensor Output vs Flow*



<sup>1</sup> Both output and flow are generalized in Figure 1-3. The curves shown apply to 0 through full output and 0 through full flow, whatever the calibrated range of the instrument.

The linearizer converts the nonlinear draw into a linear voltage that is directly proportionate to flow velocity, as shown in Figure 1-4.

Figure 1-4. *Linearized Output*



### 1.3 Features and Specifications

Some of the outstanding features of the 4440 are summarized below:

#### **Rugged Construction**

The MetalClad sensor, with its 316 stainless steel sheath, is virtually indestructible in normal use. It is highly resistant to both dirt and corrosion. Unlike pitot-tube and orifice-plate sensors, it neither clogs nor suffers significantly degraded performance when used in dirty atmospheres.

#### **Unsurpassed Accuracy**

The 4440's sensor windings are Resistor Temperature Detector (RTD)-type windings of reference-grade platinum 385.

## Dual Velocity Ranges

Every 4440 is calibrated to two velocity ranges. The low range provides maximum resolution at low flow rates. The high range measures flows of up to 12,000 SFPM. The available ranges are listed below, along with the applicable 4440 model number.

Range	Model
0-6,000 SFPM 0-2,000 SFPM	4440-4
0-12,000SFPM 0-2,000 SFPM	4440-5
0-30 SMPS 0-10 SMPS	4440M-4
0-60 SMPS 0-10 SMPS	4440M-5

Note that metric models — 4440M-4 and 4440M-5 — are calibrated in standard meters per second.

## Excellent Low-Speed Sensitivity

Unlike pitot-tube and orifice-plate sensors, the 4440 can accurately measure flows whose velocity is as low as 20 standard feet per minute.

## Switch-Selectable Temperature Reporting

The 4440's MetalClad sensor performs both velocity and temperature sensing functions. Just flip the range selection knob on the 4440 meter box, and the digital display switches from air velocity to air temperature.

## Convenient Linear Output

In addition to its built-in digital display, the 4440 also outputs a linear voltage signal suitable as input to voltmeters, chart recorders, computers, etc. Output voltage ranges are scaled to selected flow ranges and engineering units. Maximum output voltage is 2 Vdc. Refer to Table 2-1, "Linear Output Voltages," in Section 2 for a match of output voltage ranges to selected flow ranges and engineering units.

## **NBS-Traceable Calibration**

Every 4440 is factory-calibrated in a National Bureau of Standards (NBS) traceable wind tunnel. Packaged with your 4440 is a Calibration Certificate showing output voltage vs air velocity. The specifications of the 4440 are given in Table 1-1.

Table 1-1. *4440 Specifications*

<b>Sensor Construction:</b>	Reference-grade 385 platinum RTD-type windings around high-purity ceramic cores, sheathed in 316 stainless steel
<b>Accuracy:</b>	+/- (2% of reading + 1/2% of full scale)
<b>Repeatability:</b>	+/- 0.25%
<b>Response Time:</b>	1 second
<b>Calibration:</b>	Factory calibrated in NBS-traceable wind tunnel for air at 25° C and 760 mm Hg. Includes Calibration Certificate showing output voltage vs air velocity for 11 data points, including zero flow.
<b>Sensor Operating Temperature Range:</b>	-55° C to +250° C standard
	HHT rated sensor optionally available for temperatures from -55° C to +500° C
<b>Probe Construction:</b>	Stainless Steel standard



**Table 1-1 (continued)**

**Probe Support  
Dimensions:**

1" outside diameter

Preattached probe support is 10" long. The sensor and window are approximately 3 1/2" long. Thus, the probe support and sensor taken together are approximately 13 1/2" long.

4 18" probe support extenders are provided, for a total maximum length of approximately 7' 1 1/2".

**Output:**

0-2 Vdc max. (See Table 2-1 in Section 2 for actual voltages.)

**Power Supply:**

12 Vdc

**End of Section 1**

## **Section 2: Assembly and Orientation**

This section explains how to assemble the 4440 portable digital air velocity and temperature meter. It also contains detailed descriptions of the 4440's controls and connectors.

### **2.1 Assembly**

First unpack your 4440 and check to make sure that all the components shown in Figure 1-1 (refer to Section 1) are present. If any component is missing or appears to be damaged, contact Kurz Instruments at once to report the problem.

#### **2.1.1 Adding Probe-Support Extenders (Optional)**

Whether or not you use probe-support extenders depends entirely on the reach you require; the extenders do not affect the operation of the unit. You may want to read "Velocity Averaging" in Section 3 before you decide that you do not want to use any probe-support extenders.

To attach one or more probe-support extenders, follow the steps listed below:

- Step 1:        Remove the wire ties from the coiled sensor cable.
  
- Step 2:        Uncoil the cable, starting at the probe support and proceeding toward the cable connector.
  
- Step 3:        Insert the cable connector into the end of the probe-support extender that has male (outside) threads. Keep feeding cable into the end of the probe-support extender until the cable connector emerges from the other end of the extender.
  
- Step 4:        Pull cable through the probe-support extender until there is no slack cable between the preattached probe support and the probe-support extender.

**Step 5:** Thread the probe-support extender into the probe support.

Repeat steps 3 through 5 for each probe-support extender you want to attach.

### **2.1.2 Adding the Sensor-Alignment Attachment (Optional)**

Adding the sensor-alignment attachment is optional. The attachment provides you with a visual aid in aligning the 4440's sensor with the flow being measured.

The procedure for adding the attachment is described below and illustrated in Figure 2-1.

**Step 1:** Turn the sensor-alignment attachment's small tightening knob back to expose as much of the attachment's threaded area as possible, leaving just enough space between the two knurled knobs to allow the tightening knob to move freely.

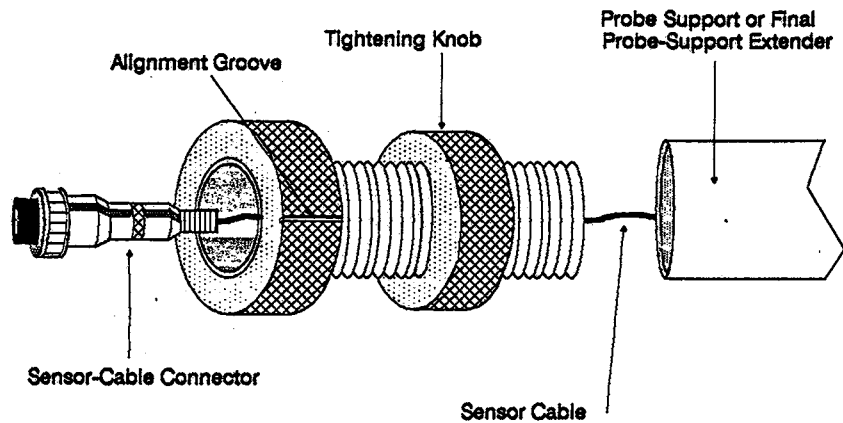
**Step 2:** Pass the sensor-cable connector through the threaded end of the attachment.

**Step 3:** Thread the attachment into the end of the probe support or probe-support extender until it is almost all the way in, but still free to turn.

**Step 4:** Align the groove on the large knurled knob with the shorter of the MetalClad sensor's two elements. (A straight line extended from the groove to the end of the probe should bisect the sensor window on the side of the shorter sensor element.)

**Step 5:** While maintaining the alignment of the groove, tighten the tightening knob against the butt of the probe support.

Figure 2-1. *Sensor-Alignment Attachment*

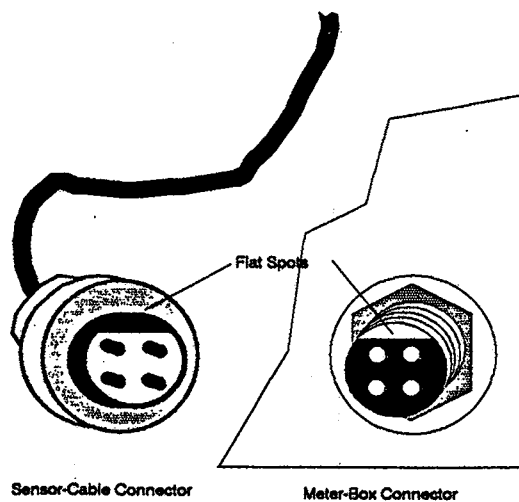


### 2.1.3 Connecting the Sensor Cable

Once you have attached any probe-support extenders you plan to use, you are ready to connect the sensor cable to the meter box.

The sensor cable plugs into the meter box connector labeled "PROBE". Note that both the cable connector and the connector on the meter box have flat spots on their plastic parts, as shown in Figure 2-2. You must align those flat spots before you can plug the cable connector into the meter box connector.

Figure 2-2. *Sensor Cable and Meter Box Connectors*



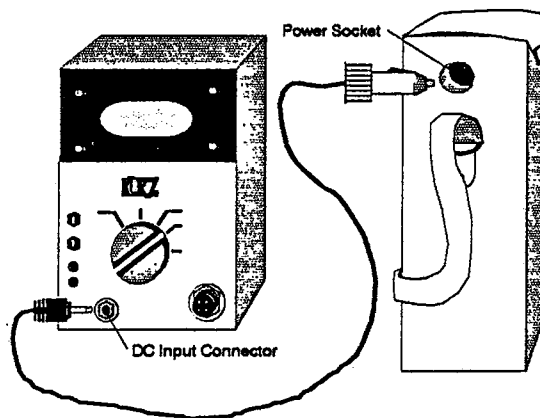
Once you have aligned the flat spots on the connectors, push the cable connector firmly into the meter box connector. Then thread the cable connector's securing ring onto the threads of the meter box connector to ensure a positive connection.

**NOTE:** Your 4440 is calibrated for the specific sensor with which it was shipped. Although it is physically possible to interchange sensors between two different 4440 units, **do not do so**. Using any sensor other than the one with which your unit was shipped seriously degrades the accuracy of the instrument.

### 2.1.4 Connecting the DC Power Cable

The DC power cable supplies power from the external battery to the meter box. The power cable ends in a jack at each end. The larger jack plugs into the socket on the side of the external battery's case. The smaller jack plugs into the unlabeled DC input connector on the front of the meter box. Figure 2-3 shows both connections.

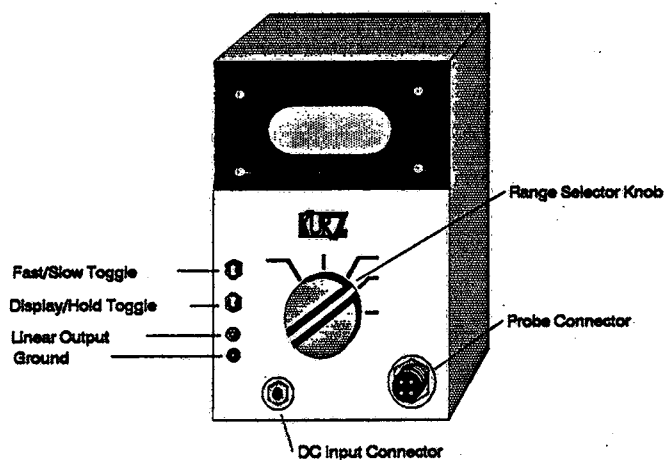
Figure 2-3. *DC Power Cable Connections*



## 2.2 Controls and Connectors

The 4440's controls and connectors are shown in Figure 2-3 and are explained individually below.

Figure 2-3. 4440 Controls and Connectors



### 2.2.1 Range Selector Knob

You can set the range selector knob to any of five positions:

- Off
- Battery Check
- High Velocity Range (0-6,000 SFPM; 0-12,000 SFPM; 0-30 SMPS; or 0-60 SMPS)
- Low Velocity Range (0-2,000 SFPM or 0-2 SMPS)
- Temperature

**Off** is of course self explanatory. Turn the unit off when it is not in use. It is also a good idea to conserve battery life by turning the unit off between readings if more than a few minutes will pass between any two readings.

**Battery Check** lets you check the charge remaining in the external battery to make sure that you have enough power for satisfactory operations. When the battery is fully charged, the digital display should read at or near 12 volts with the range selector in the battery-check position. The lower limit for successful operation is about 9 volts. A fully charged battery should power the 4440 for about 12-16 hours of normal use. If you use the unit primarily in high-velocity flows, operating time per charge will be lower, owing to the increase in current necessary to maintain the velocity sensor's overheat in a high velocity flow.

**High-Velocity Range** sets the 4440 to the higher of its two velocity ranges. Use this range whenever flow velocity exceeds the upper limit of the low-velocity range.

**Low-Velocity Range** sets the 4440 to the lower of its two velocity ranges. You should generally use this range unless flow velocity approaches or exceeds the upper limit of the low range. Although velocities within the low range are also within the high range, the low range setting provides greater resolution for low flow rates.

**Temperature** converts the 4440 from velocity sensing to temperature sensing. With the standard sensor, the temperature range reported is 0-200° C<sup>1</sup>. With the optional HHT sensor, the temperature range reported is 0-500° C.

### 2.2.2 Slow/Fast Toggle

The setting of this switch determines how frequently the 4440's digital display is updated. When the switch is in the fast position, the display is updated once a second. When the switch is in the slow position, the display is updated once every three seconds.

Ordinarily, leave this switch set to fast for the most responsive operation. If you are monitoring a very turbulent and irregular flow, however, you may want to switch to the slow setting to increase the stability of the display. That is, if the rate of flow is actually changing one or more times per second, the constant changing of the display may become distracting, and you may want to slow it down.

<sup>1</sup> The standard sensor can safely be used in flows at temperatures of up to 250° C and will accurately measure velocity in those flows. Temperatures above 200° C will be reported as 200° C, however.

### **2.2.3 Display/Hold Toggle**

The setting of this switch determines whether or not the 4440's digital display is updated. Normally, of course, you should leave this switch in the display position (up), so that the display is constantly updated to reflect the changing flow across the sensor. You can, however, hold the display of a particular reading by flipping the toggle to the hold position (down). The reading currently displayed freezes until you return the toggle to the display position.

### **2.2.4 Output Connectors**

The two output connectors on the front of the meter box allow you to connect the 4440 to a strip chart recorder, analog-to-digital interface, datalogger, or similar external device. Each connector is a standard female mini banana jack. The upper connector (+) outputs a positive linear voltage signal; the lower connector (-) is the ground.

The signal is scaled from 0 Vdc to a maximum of 2 Vdc and is directly proportionate to the range currently selected by the range selector knob. Suppose, for example, that the range 0-12,000 SFPM is selected. In this case, the maximum output signal — the signal corresponding to a flow of 12,000 SFPM — is 1.2 Vdc. A flow of 6,000 SFPM would produce an output signal of 0.6 Vdc. Table 2-1 matches linear output voltage ranges to selected velocity and temperature ranges.



Table 2-1. *Linear Output Voltages*

Range Selected	Output Voltage Range
0-2,000 SFPM	0-2 Vdc
0-6,000 SFPM	0-0.6 Vdc
0-12,000 SFPM	0-1.2 Vdc
0-10 SMPS	0-1 Vdc
0-30 SMPS	0-0.3 Vdc
0-60 SMPS	0.0.6 Vdc
0-200° C	0-2 Vdc

End of Section 2

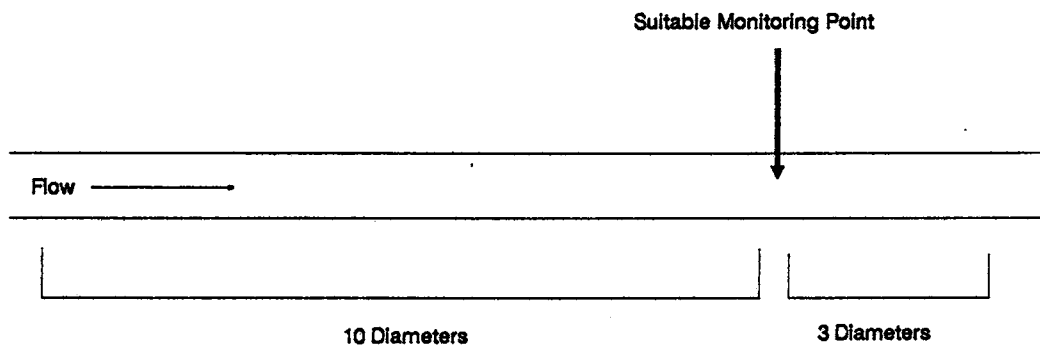
## Section 3: Operation

This section explains how to operate the 4440 portable digital air velocity and temperature meter. It contains subsections on selection of monitoring points, velocity averaging, and calculating actual (as opposed to standard) velocities.

### 3.1 Selecting a Location

If possible, you should select a monitoring point at least three pipe diameters upstream and ten diameters downstream from the nearest bend, elbow, or other obstruction in the line to be monitored. The chosen location should also provide sufficient clearance for inserting and removing the probe; that is, the clearance between the line and any obstruction should equal at least the length of the probe support, plus two or three inches for maneuver. Correct probe location is illustrated in Figure 3-1.

Figure 3-1. *Probe Location*



## 3.2 Taking a Velocity Reading

To take a velocity reading with the 4440, follow the steps listed below. This procedure assumes that you have already assembled the 4440 as instructed in Section 2.

**Step 1:** Turn the range selector knob to the desired velocity range. If you believe the flow to be measured falls within the low velocity range, use that range; it will yield more accurate results at low flow velocities. If you believe the flow to be measured exceeds the upper limit of the low velocity range, use the high velocity range. If you are unsure, use the high velocity range, and then switch to the low range later if actual measurements fall within the limits of the low range.

**Step 2:** Allow the unit to warm up for approximately 30 seconds. During this time the meter will display spurious readings, starting with a very high number and then rapidly falling. During this period the unit is establishing the correct  $R_p$  overhead. When the displayed reading stabilizes, go on to Step 3.

**Step 3:** Insert the sensor in the flow to be measured. You should generally insert the probe well into the flow — to the approximate center of the pipe, stack, or duct if you plan to take a reading of only one point (see “Velocity Averaging” below for a different strategy).

Make sure the sensor window is aligned with the air flow so that the flow passes unobstructed over the sensor elements<sup>1</sup>. If you are using the sensor-alignment attachment (described in Section 2.1.2), make sure the alignment groove is facing toward the oncoming air flow. This ensures that the  $R_{tc}$  sensor element — the shorter of the two sensor elements — is upstream, i.e., facing into the air flow.

<sup>1</sup> It is not necessary to align the sensor with great precision. As long as the sensor window is within about  $15^\circ$  of parallel to the air flow, measurement accuracy is undiminished. You can experimentally rotate the sensor and observe when the velocity reading begins to drop off.

It is important to put  $R_{tc}$  upstream because the sensor is factory calibrated in this orientation. **Reversing the orientation of the two sensor elements will significantly degrade the accuracy of your readings.**

**Step 4:** Allow approximately one second for the sensor to respond to the flow before you record the velocity reading. If the temperature of the flow is very different from the ambient temperature, you may have to allow a few seconds longer before the reading stabilizes.

**Step 5:** Take your reading.

If the flow is turbulent and irregular, use the Fast/Slow toggle to select slow display refresh (refer to Section 2).

If you want to hold the reading on the display for later reference, flip the Display/Hold toggle to the hold position (refer to Section 2).

### **3.3 Taking a Temperature Reading**

The procedure for taking a temperature reading is identical to that for taking a velocity reading, except that you select "Temperature" with the range selection knob.

### **3.4 Velocity Averaging**

When you use the 4440 to measure velocity in a line more than a few inches in diameter, it is a good idea to take readings at several points within the line and average those readings. Two related methods of velocity averaging are described below, half-traverse averaging and double-traverse averaging. Of the two, half-traverse averaging is simpler; double-traverse averaging is more accurate. Select the method that best suits your needs.